Using Stata for a memory saving fixed effects estimation of the three-way error component model^{*}

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Abstract

The paper proposes a memory saving decomposition of the design matrix to facilitate fixed effects estimation of the three-way error component model with high numbers of observations and groups.

A common way to estimate such a model is to include two of the effects as dummy variables and to sweep out the other effect by the fixed effects transformation. If the number of groups is high, the design matrix that includes the dummy variables can be prohibitively large for computer packages that need to store the whole data set in memory. The decomposition of the design matrix proposed here shows a way of how to create the cross-product matrices for the least squares normal equations without explicitly creating the dummy variables for the group effects. As the cross-product matrices are of much lower dimension than the design matrix, this procedure reduces the computer memory required considerably. For example, a model computation shows that in a linked employer-employee data set with 20 million observations and 10 thousand firms, the memory requirement drops from 800 gigabytes to 1 gigabyte. The method is implemented in Stata by making use of the new Mata environment available in Stata 9.0. Besides implementing the memory-saving estimation method, the program also takes care of identification issues (grouping algorithm) and provides useful summary statistics. The paper presents the Stata program and comments its output.

Keywords: Linked employer-employee data, fixed effects, three-way error component model

JEL classification: C23, C63

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1 Introduction

The three-way error component model has received a revived interest in labour economics due to the rising availability of linked employer-employee data which allow to analyse many problems from a different angle than before, for example by controlling for unobserved heterogeneity of workers and firms (Abowd and Kramarz 1999, Hamermesh 1999). The model applies not only to linked employer-employee data, but also to other types of matched data sets, such as for example data concerning pupils and schools.

If the researcher is concerned that unobserved heterogeneity is correlated with the observed characteristics, the model has to be estimated by fixed effects methods. In recent years, such methods have been applied to the estimation of wage equations in linked employer-employee data sets for different countries (see for example Goux and Maurin 1999, Abowd, Kramarz and Margolis 1999, Abowd, Creecy and Kramarz 2002, Gruetter and Lalive 2004, Alda 2006). Due to the size of the linked employer-employee data sets used in these studies, the authors usually encounter computer restrictions and resort to approximative methods, use time-consuming iterative solutions or apply the exact method to only a reduced number of groups.

This paper deals with one particular restriction that researchers implementing fixed effects methods of the three-way error component model may encounter: limitations of computer memory for storing a large number of dummy variables in order to capture one of the effects. The paper presents a memory-saving way to estimate the three-way fixed effects model and presents a Stata implementation of the method. The Stata implementation is a ready-to-use ado file which also takes care of the identification problem and provides useful summary statistics alongside with the estimation.

The paper proceeds as follows. Section 2 presents the model, section 3 points out the computer restrictions and shows the potential reduction in required memory size that can be gained by implementing the proposed method. Section 4 describes the decomposition of the design matrix on which the memory saving estimation procedure is based and section 5 summarizes the steps of the estimation. Section 6 presents the implementation of the method in a Stata ado-file and comments the output of the program. Section 7 concludes. Throughout the paper I refer to linked employer-employee data sets calling the two effects to be estimated person and firm effects. I will refer to stayers as those individuals that are observed in only one firm and to movers as those who are observed in several firms. Of course, the case applies also for other types of matched data sets.

2 A linear fixed effects model with three-way error component

Consider the model:

$$\tilde{y} = \tilde{X}\beta + \tilde{D}\theta + \tilde{F}\psi + \tilde{\epsilon},\tag{1}$$

where $\tilde{X}(N^* \times K)$ is the design matrix of time varying characteristics; $\tilde{F}(N^* \times J)$ is the design matrix for the firm effects; and $\tilde{D}(N^* \times N)$ is the design matrix for the person effects. N^* is the number of person-years in the dataset, J is the number of firms, N is the number of persons and K is the number of time varying regressors. The $\tilde{}$ reflects that (1) is the untransformed model.

Only two of the error components are written out explicitly. The third effect is the time-dimension which is necessary in order to identify the two other effects. For ease of notation it is subsumed in \tilde{X} together with the other time-varying regressors.

A common way to estimate such a model is to include one of the effects (here the firm effect) as dummy variables, and to sweep out the other effect (here the person effect) by the within transformation or fixed effects transformation¹. This transformation consists in subtracting the group mean (here the person mean) for all observations. The D matrix becomes the null matrix, the person effects are eliminated from the model. Abowd, Kramarz and Margolis (1999) note that this procedure is algebraically equivalent to the full dummy variable model. Andrews et al. (2006) call this procedure the "FEiLSDVj" method in order to emphasize that the model combines the classical fixed effects (FE) model and the least squares dummy variable model (LSDV), as one effect is eliminated by the fixed effects transformation and the other included as dummy variables.

Write the transformed model as:

$$y = X\beta + F\psi + \epsilon, \tag{2}$$

where ϵ is an error term satisfying the assumptions of the classical linear regression model.

¹The third effect (time effect) can also be incorporated as dummy variables. Because the time dimension is usually limited, the number of time effects is usually small and therefore does not pose a special problem.

The system of normal equations is:

$$A\left(\begin{array}{c}\beta\\\psi\end{array}\right) = B \tag{3}$$

with

$$A = \begin{pmatrix} X'X & X'F \\ F'X & F'F \end{pmatrix} \text{ and}$$

$$\tag{4}$$

$$B = \begin{pmatrix} X'y \\ F'y \end{pmatrix}$$
(5)

3 Computer restrictions

Computational problems of estimating the parameter vector from these normal equations arise

- 1. when (X, F) is too large to fit the memory, as some software packages, such as Stata, require the design matrix to be stored in memory, or
- 2. when A ist too large to be inverted, or
- 3. when the number of observations is so large that numerical problems arise when forming the sums that are elements of the cross product matrices A and B.

The main purpose of this paper is to propose a solution to point 1. However, the program set up in Stata to implement the solution also takes points 2 and 3 into account by using the Mata environment. Provided that there is enough computer memory, Mata can handle matrices of a dimension of up to 2 billion \times 2 billion compared to only 11,000 \times 11,000 in the Stata environment (Stata SE). Mata also provides computer routines with high numerical precision that can help to take into account point 3. In addition, cross-checking the results obtained with those obtained in similar but smaller data sets is another way to test whether the size of the data set poses problems of numerical precision².

Other ways to handle the estimation problem are the approximate procedures as well as two-step and iterative solutions solutions to the exact problem presented

 $^{^{2}}$ Helpful comments about that topic can be found under the thread "data set larger than RAM" on the Statalist discussion board http://www.stata.com/statalist/archive/ .

in Abowd, Kramarz and Margolis (1999), Abowd, Creecy and Kramarz (2002), Andrews et al. (2006a) and Grütter (2006)³. If the sole aim is to control for unobserved heterogeneity and not to compute the person and firm effects explicitly, the "spell fixed effects" method proposed in Andrews et al. (2006a) is a good alternative to the "FEiLSDVj" method.

Table 1 illustrates which memory requirements can come about in practical applications. The table reports two samples of the German linked employer-employee data set (LIAB) provided by the Institute for Employment Research (IAB). The first column summarizes the estimation sample used in Alda (2006) for the estimation of person and firm fixed effects in a wage equation. This is based on the longitudinal version 2 of the LIAB data. The second column of the table shows a sample that could be generated from the LIAB cross-sectional version 1.

The computation of the memory requirements is built on the assumption that all firm effects are identifyable and that the storage of each element of the design matrix requires 4 bytes. In practice, however, not all firm effects are identifyable and the memory requirement will be less. The table therefore presents an upper bound of memory requirement⁴.

When applying the "FEiLSDVj" method described above by direct creation of the time-demeaned firm dummy variables, the design matrix (X, F) must be stored. The size of this matrix is reported in the before last row of Table 1 labeled "Sum X and F". The memory requirement to store the design matrix is roughly 17 gigabytes in the sample of the first column and roughly 800 gigabytes in the sample of the second column. This is far more than the memory and, in the second example, even the hard disk space available to most researchers.

It therefore seems that the estimation of person and firm effects using the "FEiLS-DVj" method with several millions of observations and several thousands of firms would be impossible with restricted memory ressources. However, note that while the design matrix (X, F) is of dimension $(N^* \times (K + J))$, the cross-product matrices A and B given in (4) and (5) are of dimension $((K + J) \times (K + J))$ and

³The classical minimum distance estimator proposed by Andrews et al. (2006a) delivers the same coefficient estimates as the "FEiLSDVj" method, but it delivers different standard errors, because it is based on separate estimations for movers and stayers, and the error term variance of both estimations is not constrained to be equal.

⁴Andrews et al. (2006a) suggest to multiply the time-demeaned firm dummies by the least common multiple of the number of observations per person. This transforms the time-demeaned firm dummies into integers and lowers the storage requirements per element to 2 bytes. With this procedure one can half the storage requirements for the F matrix. However, in many cases this reduction will not be enough to meet the memory limitations the researcher is confronted with.

	Sample of Alda 2006	LIAB cross–sectional version
Data set	LIAB longitudinal v.2	LIAB cross-sectional v.1
Observations (N^*)	$2,\!200,\!000$	$20,\!000,\!000^{1)}$
Persons (N)	670,000	-
Firms (J)	1,900	$10,000^{2)}$
No. of regressors $(K)^{3)}$	50	50
Size of X in $(in MB)^{4}$	440	4,000
Size of F in $(in MB)^{5}$	16,720	800,000
Sum X and F (in MB)	17,160	804,000
Size of $(X, F)'(X, F)$ (in MB) ⁶⁾	15	404

Table 1: Memory requirements for two different sample configurations of German LEE data

Notes: All values in the table are approximate. ¹⁾Computed as the sum of yearly observations given in Table 2 in Alda 2005. ²⁾According to Alda et al. 2006, up to 2004 around 10,000 different establishments have taken part in the IAB establishment panel. ³⁾Hypothetical value for illustration purposes. ⁴⁾Computed as N* x K x 4 bytes. ⁵⁾Computed as N* x J x 4 bytes. ⁶⁾Computed as (K+J) x (K+J) x 4 bytes

 $((K + J) \times 1)$ only. They require much less storage space. The last row of Table 1 reports the memory requirement for A = (X, F)'(X, F), which is only 15 megabytes for the example in the first column and 404 megabytes for the example of the second column. Therefore, once the cross-product matrices have been computed, far less than 1 gigabyte of memory is sufficient to store those matrices in both of the above examples⁵.

How can A and B be computed, if the underlying design matrix (X, F) does not fit into the memory? A solution for that problem lies in the fact that each element of Aand B is a cross product sum of no more than two regressors. This implies that for computing one element of A or B, only two regressors need to be stored in memory. While the X-part of the design matrix is provided as a dataset, the F-part of the cross-product matrix can be created during the estimation process without actually generating the F-part of the design matrix, i.e. the dummy variables. The information needed for that purpose is condensed in the group identifiers. The following decomposition is based on the fact that the F matrix is a sparse matrix, i.e. large

⁵The cross product matrix B = (X, F)'y is negligibly small compared to the matrix A.

parts of it are null sub-matrices which deliver no contribution to A or B. Therefore, in the process of the formation of A and B, only certain parts of the F matrix need to be created and time and memory can be saved.

4 The decomposition

Let the persons in the dataset be indexed by i (i = 1...N) and the time periods for each individual be indexed by t $(t = 1...T_i)$. T_i is the number of time periods that individual i is observed. The total number of observations is then $N^* = \sum_i T_i$. The vector y and the design matrices X and F in (2) have row dimension N^* and rows are indexed by the index it. The columns of X are indexed k (k = 1, ...K)and the columns of F are indexed j (j = 1...J).

The decomposition starts from the idea that the A and B matrices can be decomposed by observations or subsets of observations (this idea is also developed in Ritchie 1995). For example, A(B) can be represented as a sum of matrices $A_i(B_i)$ for each individual:

$$A = \sum_{i} A_{i} = \sum_{i} \begin{pmatrix} X'_{i}X_{i} & X'_{i}F_{i} \\ F'_{i}X_{i} & F'_{i}F_{i} \end{pmatrix} \text{ and}$$
(6)

$$B = \sum_{i} B_{i} = \sum_{i} \begin{pmatrix} X'_{i} y_{i} \\ F'_{i} y_{i} \end{pmatrix},$$
(7)

where X_i is $(T_i \times K)$, F_i is $(T_i \times J)$ and y_i is $(T_i \times 1)$. The matrices involve only those observations that are associated with individual *i*.

For the current purpose it makes sense to do the individual-wise decomposition only for those parts of the matrices, where the F matrix is involved, i.e.:

$$A = \begin{pmatrix} X'X & 0\\ 0 & 0 \end{pmatrix} + \sum_{i} \begin{pmatrix} 0 & X'_{i}F_{i}\\ F'_{i}X_{i} & F'_{i}F_{i} \end{pmatrix}$$
 and (8)

$$B = \begin{pmatrix} X'y\\ 0 \end{pmatrix} + \sum_{i} \begin{pmatrix} 0\\ F'_{i}y_{i} \end{pmatrix}.$$
(9)

The decomposition continues with the idea that the F matrix has a different structure for stayers and for movers. In this context movers are defined as workers who change employer at least once during the whole observation period and stayers are those workers who never change employer.

Recall that the model is a transformed model. Group means by person have been substracted ("time-demeaning" /"within-transformation"). As stayers never change firms, the time-demeaned firm dummies are all zero. The F matrix for stayers is the null matrix.

Therefore we get:

$$A = \begin{pmatrix} X'X & 0\\ 0 & 0 \end{pmatrix} + \sum_{i \in \text{Movers}} \begin{pmatrix} 0 & X'_i F_i\\ F'_i X_i & F'_i F_i \end{pmatrix} \text{ and}$$
(10)

$$B = \begin{pmatrix} X'y \\ 0 \end{pmatrix} + \sum_{i \in \text{Movers}} \begin{pmatrix} 0 \\ F'_i y_i \end{pmatrix}.$$
(11)

(10) and (11) are important simplifications of (8) and (9). As the F matrix is the null matrix in the sub sample of stayers, the cross product sub matrices X'F, F'F and F'y only need to be computed for movers, which are usually a comparatively small fraction of the sample.⁶ As these matrices can be computed individual by individual, the F matrix does not need to exist completely at any point of time. For example, it suffices to create the matrix F_i for one individual and to compute X'_iF_i , F'_iF_i and F'_iy_i . F_i is of dimension $(T_i \times J)$ and therefore should fit the memory. However, by analysing the structure of F_i more precisely, the matrix can be reduced further and more memory space can be saved.

Look at F_{i^*} for a worker i^* who is observed at $T_{i^*} = 3$ different points in time and changes the firm once. The non time-demeaned matrix \tilde{F}_{i^*} is:

$$\tilde{F}_{i^*} = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & \dots & 0 \\ 1 & 0 & 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & 1 & 0 & \dots & 0 \end{pmatrix}$$
(12)

Worker i^* is employed during two time periods in firm 1 and during the third time period in firm 4. He is never employed in any other firm, which means that to the right the individual F matrix is filled up with zeros.

The corresponding time-demeaned design matrix of the firm effects for individual i^* is:

$$F_{i^*} = \begin{pmatrix} 1/3 & 0 & 0 & -1/3 & 0 & \dots & 0 \\ 1/3 & 0 & 0 & -1/3 & 0 & \dots & 0 \\ -2/3 & 0 & 0 & 2/3 & 0 & \dots & 0 \end{pmatrix}$$
(13)

What is important is that for each worker, only very few columns of F_{i^*} will be different from null vectors, because a given worker is employed in very few firms relative to the total set of firms. Consequently, many elements of the cross product matrices X'_iF_i , F'_iF_i and F'_iy_i are equal to zero. In the appendix (section 7), $(X'_{i^*}F_{i^*})$,

⁶The matrix F'X is the transpose of X'F an therefore in what follows it is not discussed separately.

 $(F'_{i^*}F_{i^*})$ and $(F'_{i^*}y_{i^*})$ are computed for the above example. In $(F'_{i^*}F_{i^*})$ the only nonzero elements are those where both row and column indices refer to a firm where worker *i* was employed at some moment of time. In $(X'_{i^*}F_{i^*})$ only the columns that are indexed with reference to a firm where worker *i* was employed are non-zero. In $(F'_{i^*}y_{i^*})$ only the rows that are indexed with reference to a firm where worker *i* was employed are non-zero.

A typical worker is usually employed in very few firms and thus contributes to only very few elements of the cross product matrices. F_i is a sparse matrix, and so are $(X'_{i*}F_{i*}), (F'_{i*}F_{i*})$ and $(F'_{i*}y_{i*})$. One can write F_i more compactly by leaving out the zero columns. Call this reduced matrix F_i^S . This is a $T_i \times s$ matrix, where s is the number of firms in which individual *i* was employed. In the above example, F_i^S would be a (3×2) matrix which reads:

$$F_{i^*}^S = \begin{pmatrix} 1/3 & -1/3 \\ 1/3 & -1/3 \\ -2/3 & 2/3 \end{pmatrix}$$
(14)

Instead of computing (X'_iF_i) , (F'_iF_i) and (F'_iy_i) one can compute $(X'_iF^S_i)$, $(F^{S'}_iF^S_i)$ and $(F^{S'}_iy_i)$, which saves memory and time. However, one needs the information to which firm the columns of F^S_i refer, because once the cross products are computed, the results need to be added to the correct elements of the A and the B matrix, which is not a problem because this information is stored in the group identifiers. The next section summarises the algorithm for the fixed effects estimation of the linear three-way error component model in a memory saving way.

5 The algorithm to compute the least squares solution

The memory-saving way to compute the matrices A and B of the normal equations uses the information in which firm a given worker is employed. This allows to compute only those elements of A and B that the worker contributes to. The zero elements of the sparse matrices involved are dropped from the computations. The steps are the following:

- 1. Create null matrices A of dimension $((K + J) \times (K + J))$ and B of dimension $((K + J) \times 1)$.
- 2. Compute X'X and X'y on the combined sample of movers and stayers. Fill

in these cross products at the appropriate sub matrices of A and B as shown in (8) and (9).

- 3. For each mover $i(i \in Mover)$ create the time-demeaned matrix F_i but leave out columns that are zero, call this reduced matrix F_i^S . This is a $T_i \times s$ matrix, where s is the number of firms in which individual i was employed. Now,
 - a. form $F_i^{S'}F_i^S$ and update the A matrix by adding the resulting crossproducts to the appropriate elements of A,
 - b. form $X'_i F^S_i$ as well as its transpose $(X'_i F^S_i)' = F^{S'}_i X_i$ and update the A matrix by adding the resulting cross-products to the appropriate elements of A,
 - c. form $F_i^{S'}y$ and update the *B* matrix by adding the resulting cross-products to the appropriate elements of A.
- 4. Once A and B are completed, solve for the coefficient vector (β, ψ) .

6 Implementation in Stata

This section uses a small simulated LEE data set in order to illustrate the Stata implementation of the estimation method. The memory-saving estimation of the "fixed effects least squares dummy variables regression" has been implemented in the stata ado-file *felsdvreg* which is available from the author upon request. This section shows that *felsdvreg* leads to exactly the same results that are obtained when the "FEiLSDVj" method is implemented in the usual way by creating the dummy variables in the data set. The section also comments and explains the output generated by *felsdvreg*.

The data set used for the illustration has 100 observations. It comprises 20 workers, for which the dummy variables $p1 \dots p20$ have been created, and 15 firms, for which the dummy variables $f1 \dots f20$ have been created. The dependent variable is called y, the two independent time-varying regressors are called x1 and x2.

A simple pooled linear regression of y on x1 and x2 gives the following result:

•	reg y x1 x2					
	Source	SS	df	MS	Number of obs =	100
	+-				F(2, 97) =	5.26
	Model	1121.26227	2	560.631137	Prob > F =	0.0068
	Residual	10341.1204	97	106.609489	R-squared =	0.0978
	+-				Adj R-squared =	0.0792
	Total	11462.3827	99	115.781643	Root MSE =	10.325

у		Coef.	Std. Err.	t	P> t	[95% Conf.	Interval]
x1		1.11365	.3580307	3.11	0.002	.4030576	1.824241
x2		3307562	.348666	-0.95	0.345	-1.022762	.3612493
_cons		-2.158526	1.046275	-2.06	0.042	-4.235091	0819599

The omission of person and firm fixed-effects is likely to bias the coefficient estimates if the omitted heterogeneity is correlated with the included regressors.

A common way to estimate a model with person and firm fixed effects is to include the firm effects as dummies and to eliminate the person affects by the within transformation ("FEiLSDVj" method). This can be implemented as follows:

```
. xtreg y x1 x2 f1-f15, fe i(i)
```

Fixed-effects Group variable	(within) reg (i): i	ression		Number Number	Number of obs = 1 Number of groups =			
R-sq: within between overall	= 0.6518 = 0.0000 = 0.2932			Obs per	group: min = avg = max =	1 5.0 9		
corr(u_i, Xb)	= -0.2330			F(11,69 Prob >)) = F =	11.74 0.0000		
y	Coef.	Std. Err.	t	P> t	[95% Conf.	Interval]		
x1	1.029258	.2151235	4.78	0.000	.6000987	1.458418		
x2	709482	.2094198	-3.39	0.001	-1.127263	2917009		
f1	(dropped)							
f2	(dropped)							
f3	-13.2617	3.258081	-4.07	0.000	-19.76139	-6.762004		
f4	(dropped)							
f5	.6932951	3.139439	0.22	0.826	-5.569713	6.956304		
f6	-5.433107	3.908214	-1.39	0.169	-13.22978	2.363566		
f7	3.12687	3.882176	0.81	0.423	-4.617858	10.8716		
f8	(dropped)							
f9	6.016403	4.967271	1.21	0.230	-3.893031	15.92584		
f10	-16.76837	3.245567	-5.17	0.000	-23.2431	-10.29364		
f11	(dropped)							
f12	-6.752864	3.941654	-1.71	0.091	-14.61625	1.110519		
f13	-2.526721	3.844219	-0.66	0.513	-10.19573	5.142287		
f14	-12.72366	3.047553	-4.18	0.000	-18.80336	-6.643961		
f15	(dropped)							
_cons	2.87504	1.113735	2.58	0.012	.6531994	5.09688		
sigma_u	9.170253							
sigma_e	5.4861156							
rho	.73642876	(fraction	of varia	nce due t	;o u_i)			
F test that al	l u_i=0:	F(19, 69) =	4.03	1	Prob >	F = 0.0000		

Stata drops six of the fifteen firm effects, which apparently are not identified. The coefficient estimates on x1 and x2 differ from those in the pooled regression, reflecting the effect of controlling for unobserved heterogeneity.

Some of the non-identified firm effects belong to firms without movers, because for a firm without movers the firm effect is never identified. The firms with movers can be divided into groups within which there is worker mobility, but between which there is no mobility. Within each such group, one firm effect is not identified, i.e. one firm effect has to be taken as the reference, and all other firm effects are expressed as differences from the reference firm.

In the present sample data set, two firms have no movers (firm 1 and firm 2), and the remaining firms are divided into 4 groups. Therefore, six firm effects are not identified. However, it is arbitrary which firm effect in each group is used as the reference.

The table shows to which group the firms with movers belong⁷:

Group	Firms
1	$3,\!4,\!5$
2	6,7,8,9
3	$10,\!11,\!12$
4	13,14,15

When looking at the firm dummies that have been dropped from the above estimation, we see that in the *xtreg* command firm 4 is the reference in group 1, firm 8 in group 2, firm 11 in group 3 and firm 15 in group 4.

We can repeat the estimation and decide by ourselves which firm effect to drop in each group. When dropping the first firm in each group (i.e. the firm with the lowest firm ID), the results read:

. xtreg y x1 x2 f4-f5 f7-f9 f11-f12 f14-f15, fe i(i)

Fixed-effects (within) regression	Number of obs	=	100
Group variable (i): i	Number of groups		20
R-sq: within = 0.6518	Obs per group: min	=	1
between = 0.0015	avg	=	5.0
overall = 0.0913	max	=	9
corr(u_i, Xb) = -0.5330	F(11,69)	=	11.74
	Prob > F	=	0.0000

⁷An algorithm to determine the groups is derived in Abowd et al. (2002). The algorithm is included in the program *felsdvreg* drawing on the Stata code by Andrews at al. 2006a

у	Coef.	Std. Err.	t	P> t	[95% Conf.	Interval]
x1	1.029258	.2151235	4.78	0.000	.6000987	1.458418
x2	709482	.2094198	-3.39	0.001	-1.127263	2917009
f4	13.2617	3.258081	4.07	0.000	6.762004	19.76139
f5	13.95499	2.818964	4.95	0.000	8.331314	19.57867
f7	8.559977	3.882525	2.20	0.031	.8145504	16.3054
f8	5.433107	3.908214	1.39	0.169	-2.363566	13.22978
f9	11.44951	4.792492	2.39	0.020	1.888749	21.01027
f11	16.76837	3.245567	5.17	0.000	10.29364	23.2431
f12	10.01551	3.407205	2.94	0.004	3.218319	16.8127
f14	-10.19694	3.074528	-3.32	0.001	-16.33046	-4.063427
f15	2.526721	3.844219	0.66	0.513	-5.142287	10.19573
_cons	-6.044057	1.03021	-5.87	0.000	-8.09927	-3.988844
+- sigma_u	10.169633					
sigma_e	5.4861156					
rho	.77458273	(fraction	of varia	nce due t	co u_i)	
F test that all	i=0:	F(19, 69) =	8.6	4	Prob >	F = 0.0000

The relative effect between firms in the same group are exactly the same (e.g. the difference between f6 and f7 is 8.559977 in both *xtreg* estimations), but between groups they are not the same, because relative firm effects between groups are affected by the decision which firm serves as the reference in each group. In fact, relative firm effects between groups are not identified and therefore firm effects should not be compared between groups.

The person effects can be recovered by:

. predict p . tab i, su	eff m(p	xt, u effxt)		
	T	Sur	nmarv of u[i]	
i	İ	Mean	Std. Dev.	Freq.
1		-9.3451653	0	1
2	Ι	-3.7514441	0	2
3	Ι	12.987279	0	2
4	Ι	-4.6659427	0	4
5	Ι	-3.8792346	0	1
6	Ι	1.1379685	0	6
7	Ι	44613671	0	6
8	Ι	.45241559	0	4
9	Ι	-16.23423	0	1
10	Ι	-12.18615	0	9
11	Ι	40414947	0	9
12	Ι	-3.9539671	0	6
13	Ι	-11.948536	0	6
14	Ι	-4.2723632	0	5
15	Ι	1.7324725	0	2

	-+-			
20	Ι	11.061296	0	8
19	Ι	14.427181	0	9
18	I	21.664909	0	8
17	I	-13.570383	0	7
16	Ι	-11.586735	0	4

In this small data set, the same results can be obtained by including all person and firm effects in a pooled regression:

. reg y x1 x2 p1- p20 f4-f5 f7-f9 f11-f12 f14-f15, noc

Source	SS	df	MS		Number of obs	= 100
+-					F(31, 69)	= 10.46
Model	9754.77005	31 314.0	670002		Prob > F	= 0.0000
Residual	2076.72508	69 30.09	974649		R-squared	= 0.8245
+-					Adj R-squared	= 0.7456
Total	11831.4951	100 118.3	314951		Root MSE	= 5.4861
y l	Coef.	Std. Err.	t	P> t	[95% Conf.	Interval]
x1	1.029258	.2151235	4.78	0.000	.6000987	1.458418
x2	709482	.2094198	-3.39	0.001	-1.127263	2917009
p1	-15.38922	5.5063	-2.79	0.007	-26.37399	-4.404454
p2	-9.795501	3.908692	-2.51	0.015	-17.59313	-1.997874
p3	6.943222	3.907763	1.78	0.080	8525509	14.739
p4	-10.71	2.743058	-3.90	0.000	-16.18225	-5.237749
p5	-9.923292	5.590565	-1.78	0.080	-21.07616	1.229581
p6	-4.906089	2.592838	-1.89	0.063	-10.07866	.266481
p7	-6.490194	2.584415	-2.51	0.014	-11.64596	-1.334426
p8	-5.591642	4.256923	-1.31	0.193	-14.08397	2.900687
p9	-22.27829	6.193958	-3.60	0.001	-34.63489	-9.921679
p10	-18.23021	2.742264	-6.65	0.000	-23.70087	-12.75954
p11	-6.448207	3.084513	-2.09	0.040	-12.60164	2947709
p12	-9.998024	2.75384	-3.63	0.001	-15.49178	-4.504264
p13	-17.99259	2.770329	-6.49	0.000	-23.51925	-12.46594
p14	-10.31642	3.662598	-2.82	0.006	-17.6231	-3.009737
p15	-4.311585	4.374143	-0.99	0.328	-13.03776	4.414591
p16	-17.63079	3.830932	-4.60	0.000	-25.27329	-9.988293
p17	-19.61444	2.297134	-8.54	0.000	-24.1971	-15.03178
p18	15.62085	3.046805	5.13	0.000	9.542643	21.69906
p19	8.383124	3.515348	2.38	0.020	1.370196	15.39605
p20	5.017239	2.268042	2.21	0.030	.4926188	9.541858
f4	13.2617	3.258081	4.07	0.000	6.762004	19.76139
f5	13.95499	2.818964	4.95	0.000	8.331314	19.57867
f7	8.559977	3.882525	2.20	0.031	.8145504	16.3054
f8	5.433107	3.908214	1.39	0.169	-2.363566	13.22978
f9	11.44951	4.792492	2.39	0.020	1.888749	21.01027
f11	16.76837	3.245567	5.17	0.000	10.29364	23.2431
f12	10.01551	3.407205	2.94	0.004	3.218319	16.8127
f14	-10.19694	3.074528	-3.32	0.001	-16.33046	-4.063427
f15	2.526721	3.844219	0.66	0.513	-5.142287	10.19573

The coefficient estimates on x1 and x2 as well as the corresponding standard errors are exactly the same as in the preceding two *xtreg* estimations. Person and firm effects can be read directly from the coefficient estimates. The firm effects are exactly the same than in the preceding *xtreg* estimation (p.12). The person effects only differ by a constant of -6.044057 which is the constant estimated in the *xtreg* model. *xtreg* is programmed such that the mean person effect is subtracted from the person effects and displayed as the regression constant. In other words, *xtreg* normalizes the sum of all person effects to zero.

As described in the previous section, the explicit creation of all firm dummies combined with the use of *xtreg* (let alone the creation of all person and firm dummies with the use of *reg*) can require more computer memory than is available. In the case when there is a large number of firms it can therefore be necessary to apply a memory-saving way to the solution of the "FEiLSDVj" estimator. I have programmed the algorithm presented in the preceding section as a Stata ado-file called *felsdvreg*. This routine can be applied to the present data set as follows:

felsdvreg y x1 x2, i(i) j(j) f(feffhat) p(peffhat) m(mover) g(group)
xb(xb) r(res) mnum(mnum) pobs(pobs)

The options are the following: The option $\mathbf{i}()$ is used to pass the variable name of the person ID, the option $\mathbf{j}()$ does the same for the firm ID. The options $\mathbf{p}()$ and $\mathbf{f}()$ define names of new variables to be created in order to store the person and firm effects after estimation. So do the options $\mathbf{xb}()$ and $\mathbf{res}()$ to store the linear combinations $x'\hat{\beta}$ and the residual $\hat{\epsilon}$. The remaining options define names of new variables that store a dummy variable that indicates a person who is a mover ($\mathbf{m}()$), a group variable that counts and identifies the number of groups of firms that are connected through mobility ($\mathbf{g}()$), a variable that contains the number of movers per firm ($\mathbf{mnum}()$) and a variable that stores the number of observations per persons ($\mathbf{pobs}()$).

In the following, the output is commented in several steps:

```
. felsdvreg y x1 x2, i(i) j(j) f(feffhat) p(peffhat) m(mover) g(group)
xb(xb) r(res) mnum(mnum) pobs(pobs)
Selecting sample and dropping superfluous observations 17:21:30
Preserve dataset 17:21:30
Fit restricted model 17:21:30
Generate smooth firm and person ids 17:21:30
Sort 17:21:30
Determine stayers and movers 17:21:30
41 Unique worker firm combinations.
```

	in.	employed	vorkers are	firms	Number of
Cum.		Percent	Freq.	6	00000
35.00		35.00	 7	+ 1	
70.00		35.00	7	2	
90.00		20.00	4	3	
100.00		10.00	2	4	
		100.00	20	+ 1	Tota
		persons:	out of all	movers	Number of
Cum.		Percent	Freq.	r	move
35.00		35.00	7	+ 0	
100.00		65.00	13	1	
		100.00	20	+ 1	Tota

Number of observations per person:

Cum.	Percent	Freq.	pobs
15.00	15.00	3	1
30.00	15.00	3	2
45.00	15.00	3	4
50.00	5.00	1	5
70.00	20.00	4	6
75.00	5.00	1	7
85.00	10.00	2	8
100.00	15.00	3	9
	100.00	20	Total

Distribution of number of movers per firm:

00000F	Freq.	Percent	Cum.
0	2	13.33	13.33
1- 5	7	46.67	60.00
6- 10	5	33.33	93.33
11-20	1	6.67	100.00
Total	15	100.00	

Until here, the program has analysed the structure of the data set. The first table tells us in how many firms the workers are employed. The seven workers employed in only one firm are stayers. Out of the remaining 13 workers, 7 are observed in two firms, 4 in three firms and 2 in four firms. The second table is a summary of the first and gives the total number of stayers and movers. The third table indicates the numbers of observations per person. For example, 3 workers are observed only

at one point in time, 3 workers are observed 9 times, etc.

The fourth table shows the distribution of the number of movers per firm. The purpose of this table is to get an impression of the quality of the estimation of the firm effects. The estimation of the firm effects is better the more movers there are and one might think of the firm effects that are identified by few movers as effects that are poorly measured. In this example data set two firms have no movers and all 15 firms have less than 20 movers.

The 15 firms can be divided into groups within which there is worker mobility, but between which there is no mobility. As noted above, within each such group, one firm effect is not identified, i.e. one firm effect has to be taken as the reference, and all other firm effects are expressed as differences from the reference. The *felsdvreg* program goes on by defining the groups⁸:

Group firms without movers under artificial firm IDs 17:21:31 Determine number of groups 17:21:31

New variable group contains grouping indicator 100 person-years (14 firms) to be allocated. Group 0 contains firms without movers. Group 0: 10 person-years allocated to groups. + 10(1) Left: 90(13) Group 1: 36 person-years allocated to groups. + 26(3) 64 left. Group 2: 51 person-years allocated to groups. + 15(4) 49 left. Group 3: 75 person-years allocated to groups. + 24(3) 25 left. Group 4: 100 person-years allocated to groups. + 25(3) 0 left.

		Person-years	Persons	Mover	Firms
 group		N(000000)	N(000009)	sum(00000D)	N(000008)
0		10	5	0	2
1		26	5	3	3
2		15	2	2	4
3		24	5	5	3
4		25	3	3	3
 Total		100	20	13	15

Note: Group 0 in the table regroups firms without movers. No firm effect in group 0 is identified.

15-2-4 = 9 firm effects are identified.

Computed as: number of firms - number of firms without movers - number of groups (excl. group 0)

The two firms without movers are gathered in group 0. The remaining firms of the sample are divided into 4 groups. The table shows the number of person-years,

 $^{^{8}}$ The grouping algorithm incorporated in *felsdvreg* draws on the Stata implementation by Andrews et al. (2006a)

persons, movers and firms in each of the groups. As indicated, only 9 of the 15 firm effects are identified because 2 firms have no movers and their firm effects cannot be identified, and 4 more firms effects are not identified because they serve as reference in their groups.

The remaining estimation output reads as follows:

Time-demean variables 17:21:31 Start Mata environment 17:21:31 Compute Total sum of squares 17:21:31 Create moment matrices 17:21:31 Filling in elements for movers 17:21:31 Take out unidentified firm effects 17:21:31 Dimension A 11 Solving for beta 17:21:31 Restore dataset 17:21:31 Generate smooth firm and person IDs again 17:21:31 Predicting x'b and assigning firm effects 17:21:31 Computing residuals and person effects 17:21:31 Solving for standard errors 17:21:31 N=100 _____ Coef. Std. Err. t P>|t| [95% Conf. Interval] _____+ x1 | 1.029258 .2151235 4.78 0.000 .6000987 1.458418 x2 | -.7094819 .2094198 -3.39 0.001 -1.127263 -.2917009 F-test that all person and firm effects are equal to zero: F(28,69)=9.81Prob > F = 8.711e-15If the covariances are positive, the following can be interpreted as shares in explaining the variance of y: Cov(y, xb) / Var(y):.10029458 Cov(y, peffhat) / Var(y): .56511312 Cov(y, feffhat) / Var(y): .15341486 Cov(y, res) / Var(y): .18117743 Job Done! 17:21:31

Note that the coefficient estimates on x1 and x2 and their standard errors are exactly the same as in the estimations shown above, where the dummy variables where included 'manually'.

The variance decomposition at the end of the output gives an indication of how strongly the four components (i) observed time-varying characteristics, (ii) person effects, (iii) firm effects and (iv) the residual contribute to explaining the variance of the dependent variable. The shares sum to 1, however, the covariances indicated can become negative and then it becomes difficult to interpret the numbers as shares. We now look at the person and firm effects:

	I	Summary of feffhat		
j		Mean	Std. Dev.	Freq.
1	-+-	0	0	3
2	Ì	0	0	7
3	Ì.	0	0	8
4	I.	13.261698	0	9
5	Ι	13.954993	0	9
6	Ι	0	0	5
7	Ι	8.5599766	0	4
8	Ι	5.4331064	0	4
9	Ι	11.44951	0	2
10	Ι	0	0	10
11	Ι	16.768372	0	9
12	Ι	10.015507	0	5
13	Ι	0	0	7
14	Ι	-10.196942	0	13
15		2.5267205	0	5
Total	+-	4.048878	8.2788071	100

. tab j, sum(feffhat)

. tab i, sum(peffhat)

i	 	Summ Mean	ary of peffhat Std. Dev.	Freq.
1	·+- 		0	1
2	i	-9.7955017	0	2
3	i	6.943222	0	2
4	İ	-10.71	0	4
5	Ì	-9.9232922	0	1
6	Ì.	-4.9060888	0	6
7	Ì.	-6.4901938	0	6
8	Ì.	-5.5916419	0	4
9	I	-22.278286	0	1
10	I	-18.230206	0	9
11	I	-6.4482064	0	9
12	I	-9.998024	0	6
13	I	-17.992594	0	6
14	Ι	-10.316421	0	5
15	Ι	-4.3115845	0	2
16	Ι	-17.630793	0	4
17	Ι	-19.614441	0	7
18	Ι	15.620852	0	8
19	Ι	8.3831244	0	9
20		5.0172386	0	8
Total	+-	-6.0440572	10.846544	100

The firm effect of the firm without movers and of the reference firm in each group are set to zero. The firm effects are exactly the same as in the second *xtreg* estimation (p.12) and the pooled estimation with the person and firm dummies (p.14). The person effects are the same as in the pooled regression with the person and firm dummies (p.14), and they differ from the effects of the second *xtreg* regression

(p.12) only by the constant -6.044057 of the *xtreg* model, because *felsdvreg* does not by default normalize the sum of the person effects to $zero^9$.

After the estimation, the researcher may be interested in correlating the person and firm effects with each other or with other regressors. However, it should be kept in mind that what is actually identified are relative person and firm effects within each group, and that person and firm effects of different groups should not be compared. This can be illustrated by computing the correlation of person and firm effects over all groups with different normalisations.

The first command correlates the person and firm effects over all groups, the second command correlates only the effects of group 1:

Now we normalise the firm and person effects so that they sum to zero within each group by subtracting the average group firm and the average group person effect. We construct a new variable *gmean* which for each group is equal to the sum of the mean firm and the mean person effect of the group. After this normalisation, the person and firm effects are deviations from the group means that are stored in *gmean*. After that we compute the correlation over all groups and the correlation

 $^{^{9}}$ If the option *cons* is chosen in *felsdvreg*, it does normalize the sum of the person effects to zero and displays a regression constant.

using only the effects of group 1:

. by group: egen pmean=mean(peffhat)

- . by group: egen fmean=mean(feffhat)
- . gen peffnorm=peffhat-pmean
- . gen feffnorm=feffhat-fmean
- . gen gmean=pmean+fmean

```
. tab group, sum(gmean)
```

1	Summary of gmean		
group	Mean	Std. Dev.	Freq.
0	-7.3857074	0	10
1	-1.2363138	0	26
2	-2.6100435	0	15
3	-7.2913418	0	24
4	4.8250484	0	25
Total	-1.9951788	4.6572344	100

The normalisation has changed the result from the correlation over all groups¹⁰. It is now 0.0227 whereas before it was -0.5645. The result of the correlation within the group of -0.2006 is still the same. One could argue that the normalisation of person and firm effects to an equal group mean makes comparison across groups more appropriate and therefore the correlation over all groups after normalisation is appropriate whereas the one before normalisation was not. However, it seems difficult to argue that a deviation of +1 from a group mean of -7.29 of group 3

¹⁰This normalization is not exactly implemented in *felsdvreg*, But the program has two options for normalization: The option *normalize* normalizes the firm effects to mean zero within each group and adds the mean firm effects that are subtracted in each group to the person effects. The option *cons* normalizes the person effects to sum to zero over all observations and displays the overall mean person effect as the regression constant. Both options can be combined.

means the same as a deviation of +1 from the group mean of 4.82 in group 4. The normalisation does not change the fact that relative firm effects within groups are identified but relative firm effects between groups are not identified. It is therefore preferable to correlate only effects of the same group.

Andrews et al. (2006b) show that the correlation between worker and firm effects is biased and that the bias is greater the lower the observed worker mobility between firms. After estimation one may therefore want to select firm and person effects that fulfill certain minimum requirements with respect to the minimum number of movers per firm or the minimum number of observations per person. This is possible with the variables defined in the options **mnum()** and **pobs()** and returned by *felsdvreg*.

7 Conclusion

The paper has proposed a memory saving decomposition of the design matrix to facilitate fixed effects estimation of the three-way error component model. This is applicable, for example, to linked employer-employee data sets but it is also applicable to other matched data that allow to estimate a three-way error component model, such as pupil and school effects for example.

A common way to estimate such a model is to take into account one of the effects by including dummy variables, and to sweep out the other effect by the within transformation (fixed effects transformation). If the number of groups is high, creating and storing the dummy variables can require much computer memory space. The paper has presented two model samples for the estimation of person and firm effects in German linked employer-employee data, where the storage requirements would be 17 and 800 gigabytes respectively. To date, this requirement is prohibitively high for many researchers. The decomposition of the design matrix presented in this paper reduces the storage requirements in the model samples to below 1 gigabyte. A Stata ado file for the memory-saving computation of the fixed effects model has been described. Besides implementing the memory-saving estimation method, the program also implements a grouping algorithm to determine the identified effects and provides useful summary statistics. The program is available from the author upon request.

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Appendix

In the above example, $X'_{i^*}F_{i^*}$, $F'_{i^*}F_{i^*}$ and $F'_{i^*}y_{i^*}$ are:

$$F'_{i^*}F_{i^*} = \begin{pmatrix} 1/3 & 1/3 & -2/3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ -1/3 & -1/3 & 2/3 \\ 0 & 0 & 0 \\ \vdots & \vdots & \vdots \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1/3 & 0 & 0 & -1/3 & 0 & \dots & 0 \\ 1/3 & 0 & 0 & -1/3 & 0 & \dots & 0 \\ -2/3 & 0 & 0 & 2/3 & 0 & \dots & 0 \\ -2/3 & 0 & 0 & 2/3 & 0 & \dots & 0 \end{pmatrix}$$
$$= \begin{pmatrix} \phi_{i11} & 0 & 0 & \phi_{i14} & 0 & \dots & 0 \\ 0 & 0 & 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & 0 & 0 & \dots & 0 \\ 0 & 0 & 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & 0 & \dots & 0 \end{pmatrix},$$
(15)
$$\phi_{i11} = (\frac{1}{3})^2 + (\frac{1}{3})^2 + (\frac{-2}{3})^2 \\\phi_{i14} = (\frac{1}{3})(\frac{-1}{3}) + (\frac{1}{3})(\frac{-1}{3}) + (\frac{-2}{3})(\frac{2}{3}) \\\phi_{i44} = (\frac{-1}{3})^2 + (\frac{-1}{3})^2 + (\frac{2}{3})^2 \end{pmatrix}$$

$$X_{i^{*}}^{\prime}F_{i^{*}} = \begin{pmatrix} x_{i11} & x_{i21} & x_{i31} \\ x_{i12} & x_{i22} & x_{i32} \\ \vdots & \vdots & \vdots \\ x_{i1K} & x_{i2K} & x_{i3K} \end{pmatrix} \begin{pmatrix} 1/3 & 0 & 0 & -1/3 & 0 & \dots & 0 \\ 1/3 & 0 & 0 & -1/3 & 0 & \dots & 0 \\ -2/3 & 0 & 0 & -1/3 & 0 & \dots & 0 \\ -2/3 & 0 & 0 & 2/3 & 0 & \dots & 0 \end{pmatrix}$$
$$= \begin{pmatrix} \xi_{i11} & 0 & 0 & \xi_{i14} & 0 & \dots & 0 \\ \xi_{i21} & 0 & 0 & \xi_{i24} & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \xi_{iK1} & 0 & 0 & \xi_{iK4} & 0 & \dots & 0 \end{pmatrix},$$
(16)
$$\xi_{ij1} = (\frac{1}{3})x_{i11} + (\frac{1}{3})x_{i21} + (\frac{-2}{3})x_{i31}$$
$$\xi_{ij4} = (\frac{-1}{3})x_{i11} + (\frac{-1}{3})x_{i21} + (\frac{2}{3})x_{i31}$$

$$F_{i^{*}}y_{i^{*}} = \begin{pmatrix} 1/3 & 1/3 & -2/3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \\ -1/3 & -1/3 & 2/3 \\ 0 & 0 & 0 \\ \vdots & \vdots & \vdots \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} y_{i1} \\ y_{i2} \\ y_{i3} \end{pmatrix} = \begin{pmatrix} v_{i1} \\ 0 \\ v_{i4} \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

$$v_{i1} = (\frac{1}{3})y_{i1} + (\frac{1}{3})y_{i2} + (\frac{-2}{3})y_{i3}$$

$$v_{i4} = (\frac{-1}{3})y_{i1} + (\frac{-1}{3}yx_{i2} + (\frac{2}{3})y_{i3}$$

$$(17)$$